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ABSTRACT OF THE DISCLOSURE

The method according to the invention allows to determine the yaw angle of a satellite from the reading of two different sensors measuring the roll and/or pitch angles, provided that  
5 the reference point of the two sensors are not identical. A description is given basically for geostationary satellites but the method can be applied directly to satellites which are stationary with respect to any star. The method can be employed for circular and non-circular orbits.

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